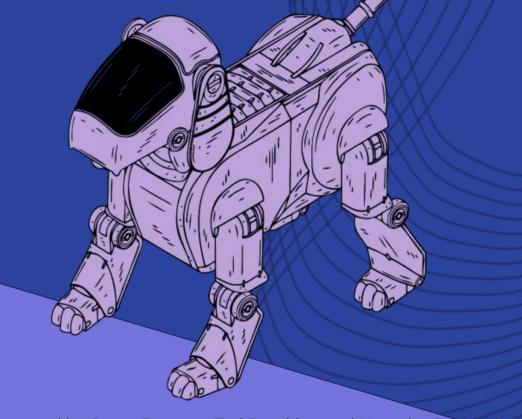


LEGO Spike Breakdancing Robot

Level 2 – Scratch

At Home





Content created by Grace Bennett, Teri Dawkins and Natasha Parbhakar

Introduction

One of the best ways to relax and relieve stress is to put on some music and have a dance! But dancing can be boring when you're by yourself...







Task

LEGO Breakdancing Robot

In this project, you will make a breakdancing robot buddy who will dance along with you to all your favourite songs!

We will be using the <u>LEGO Spike Prime Kit</u> for this resource.





Process

LEGO Breakdancing Robot

- Build your LEGO robot.
- Code the movement of the legs, arms and the blinking of the light matrix.
- Make it your own!



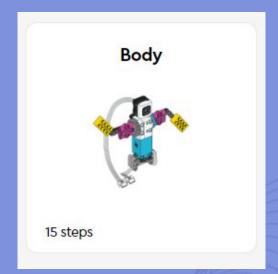


Build the LEGO Spike Breakdancing Robot

Before we can code our robot, you need to assemble it!



Click <u>here</u> for the instructions for building the Legs



Click <u>here</u> for the instructions for building the Body



Step 2Setting up the hub



Before we can start programming our hub, we need to load up the LEGO Education Spike App.

The app is compatible across most devices, like iOS and Android.

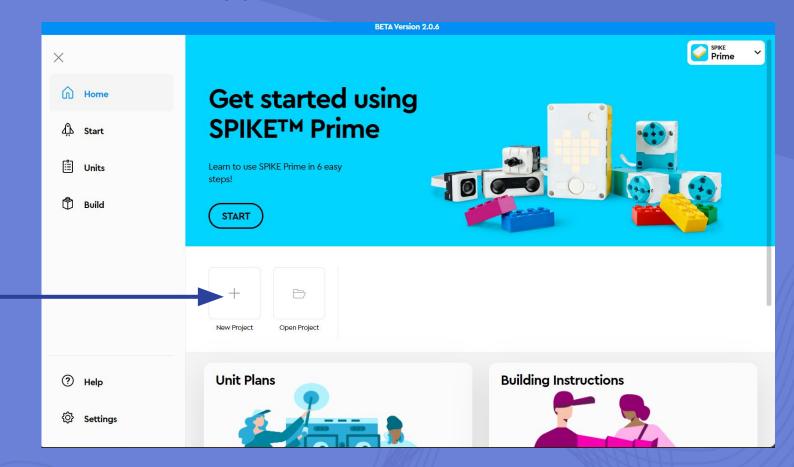
You can also access it online – click <u>here</u> to open the web app.



Select the SPIKE Prime option.



Load onto the Spike website or app



Click the 'New Project' button



Step 4 Connect your hub



Click the button in the top left corner to connect your Hub.

You can connect your Hub via Bluetooth or using a USB cable.





Syncing the legs of our robot

Drag and drop these code blocks into the central code panel.

This stack places the "break dancing" robot in position, ready to dance!





Syncing our robot's legs

Next, drag and drop these code blocks into the central code panel.

This stack will turn the motors 10 times.

You can adjust the timing here to mess with how in sync your robot is with the music!

```
when I receive GO! 
repeat 10

F v run > v for 1 rotations v

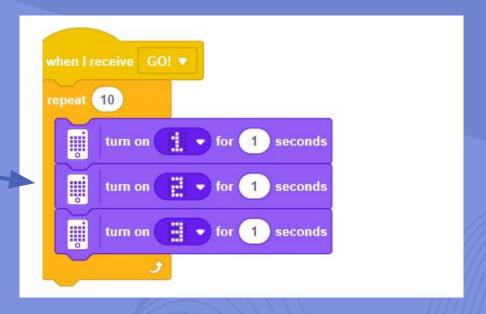
wait 1 seconds
```



Syncing our robot's legs

Next, drag and drop these code blocks into the central code panel.

This stack will light up the matrix on the hub!





At this stage, only our robot's legs seem to be dancing!

A true dancer uses their whole body so...

```
F ▼ set speed to 80 %
    F ▼ go shortest path ▼ to position 0
wait 1 seconds
     F ▼ run 🖒 ▼ for 1 rotations ▼
wait 1 seconds
repeat 10
     turn on for seconds
     turn on for 1 seconds
 turn on for 1 seconds
```



...change your code to incorporate the motors for both the arms and legs

```
D+F v set speed to 80 %
    D+F ▼ go shortest path ▼ to position 0
   1 seconds
 D+F v run 5 v for 1 rotations v
 wait 1 seconds
repeat 10
     turn on for seconds
     turn on for seconds
 turn on for 1 seconds
```



Conclusion

Learning outcomes

- ✓ Learn to sync up the hub
- Experiment with different timings to make your robot dance in fun ways!
- ✓ Use code to change the output of a device!

Congratulations!

You have completed the project

